Treizième École de Mécanique des Fluides Numérique Outils et méthodes multi-échelles Ile de Porquerolles, June 2th - 8th, 2013

Two-Scale Convergence and Two-Scale Numerical Methods

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Two-Scale Convergence And also Homogenization Typical proofs Definitions and results

Hyperbolic PDEs Order 0 Order 1

Two-Scale Numerics Algorithms Implementat

Two-Scale Convergence and Two-Scale Numerical Methods

Emmanuel Frénod¹

June 7th and 8th, 2013

¹LMBA (UMR 6205), Université de Bretagne-Sud, F-56017, Vannes, France. emmanuel.frenod@univ-ubs.fr http://web.univ-ubs.fr/lmam/frenod/index.html Two-Scale Convergence and Two-Scale Numerical Methods

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Order 1

Numerics Algorithms

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Two-Scale Convergence first statements

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G. Nguetseng.

A general convergence result for a functional related to the theory of homogenization.

SIAM Journal on Mathematical Analysis, 20(3):608–623, 1989.

G. Nguetseng.

Asymptotic analysis for a stiff variational problem arising in mechanics.

SIAM Journal on Mathematical Analysis, 21(6):1394–1414, 1990.

G. Allaire.

Homogenization and Two-Scale Convergence.

SIAM Journal on Mathematical Analysis, 23(6):1482–1518, 1992.

The simplest example I know to introduce Homogenization

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Figure : Composite material - macroscopic shape and a microstructure - Ratio size of the microstructure on the size of the material is ε .

 u^{ε} : Temperature field

$$\nabla \cdot \left[a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon} \right] = 0 \quad \text{within the material,} \\ u^{\varepsilon} \quad \text{given on the boundary of the material,}$$















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- a^ε(x, ^x/_ε) can model a wide range of microscopic oscillations or heterogeneities.
- This is why we use it in the model.

Remark

Two-Scale Convergence is based on this capability

Remark

- IF ξ → a^ε(x, ξ) periodic, THEN microscopic scale variations are qualified of high frequency periodic oscillations.
- Two-Scale Convergence is essentially designed for this context.

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Back to : the simplest example I know to introduce Homogenization

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 $u^{arepsilon}$: Temperature field $abla \cdot \left[a^{arepsilon}(\mathbf{x}, rac{\mathbf{x}}{arepsilon})
abla u^{arepsilon}
ight] = 0$ within the material,

 u^{ε} given on the boundary of the material,

IF Solved with a numerical method INDUCES : $\Delta x \ll \varepsilon$

- IF interested in the tiny variation of *u*^ε, WHY NOT (?)
- OTHERWISE: Clearly NOT REASONNABLE

Homogenization Goal

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Two-Scale Numerics Algorithms Implementati Find an operator \mathcal{H} (that neither contains nor generates oscillations of size ε) Such that μ

 $\mathcal{H}u = 0$ within the material,

 $u = u_{\text{Given}}$ on the boundary of the material,

close to u^{ε} (in some sense)

$$\nabla \cdot \left[a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon}\right] = 0 \quad \text{within the material,}$$

 $u^{\varepsilon} = u_{\text{Given}}$ on the boundary of the material,

INDEPENDENTLY of *u*Given

This means

- \mathcal{H} must induce average effect of oscillations in u
- In some sense: $\mathcal{H} = \lim_{\varepsilon \to 0} \nabla \cdot a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla$

Homogenization Theory

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Two-Scale Numerics Algorithms Implementati Homogenization Theory gathers a collection of methods that allow to build operators ${\cal H}$ satisfying the required constraint for every problem - containing or generating oscillations or heterogeneities - we can imagine.

Asymptotic Expansion: First Homogenization method set out by Engineers in the 1970s

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In the case of
$$\nabla \cdot \left[a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon}\right] = 0$$
:
 $u^{\varepsilon}(\mathbf{x}) = U(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) + \varepsilon U_1(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) + \varepsilon^2 U_2(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) + \dots,$
 $U(\mathbf{x}, \boldsymbol{\xi}), U_1(\mathbf{x}, \boldsymbol{\xi}), U_2(\mathbf{x}, \boldsymbol{\xi}), \dots$ periodic with respect to $\boldsymbol{\xi}$.

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Gathering terms in factor of ε^{-2} , ε^{-1} , ε^{0} , ε , ε^{2} , ...:

Y

$$H_{-2}U = 0, \ H_{-1}U_1 = \mathcal{I}(U), \ H_0U_2 = \mathcal{I}'(U, U_1), \ \dots$$

Get well-posed equations for U, U_1 , U_2 , ...

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Mathematical justification of Asymptotic Expansion

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Two-Scale Numerics Algorithms Implementat Needed:

$$\left\|u^{\varepsilon}(\mathbf{x})-U(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\right\|_{?}
ightarrow0,$$

or in a weaker sense:

$$\left(u^{\varepsilon}(\mathbf{x}) - U(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})\right) \rightharpoonup 0$$

For higher orders, needed:

$$\left(\frac{u^{\varepsilon}(\mathbf{x})-U(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})}{\varepsilon}-U_1(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\right)\to 0,$$

$$\left(\frac{1}{\varepsilon}\left(\frac{1}{\varepsilon}\left(u^{\varepsilon}(\mathbf{x})-U(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\right)-U_{1}(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\right)-U_{2}(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\right)\to0,$$

and so on, in some sense.

Tools for mathematical justification of Asymptotic Expansion - 1

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For Heat Equation with Dirichlet boundary conditions:

$$\nabla \cdot \left[a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon} \right] = 0 \quad \text{within the material,}$$
$$u^{\varepsilon} = u^{\varepsilon} \qquad \text{on the boundary of the material}$$

uGiven

Maximum Principle and boundary estimates WORKS. SEE

A. Bensoussan, J. L. Lions, and G. Papanicolaou. Asymptotic analysis for periodic structures. Studies in Mathematics and its Applications, Vol. 5. North Holland, 1978.

For any all problem: DOES NOT WORK.

Tools for mathematical justification of Asymptotic Expansion - 2 : "Oscillating Test Function Method"

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🚺 L. Tartar.

Cours Peccot. *Collège de France*, 1977.

F. Murat.

H-convergence.

Séminaire d'Analyse Fonctionnelle et Numérique d'Alger, 1977.

L. Tartar.

The General Theory of Homogenization. A Personalized Introduction. Springer Verlag, dec 2009.

Brief overview of Oscillating Test Function Method

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Weak Formulation with Oscillating Test Functions (WFWOTF).

$$\int_{\mathsf{Material}} \nabla \cdot \left[a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon}(\mathbf{x}) \right] \varphi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \, d\mathbf{x} = 0,$$

By the Stokes Formula:

$$\int_{\mathsf{Material}} a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon}(\mathbf{x}) \cdot \nabla \left[\varphi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})\right] d\mathbf{x} = \int_{\mathsf{Boundary}} \mathsf{Something},$$

or

$$\int_{\text{Material}} a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \nabla u^{\varepsilon}(\mathbf{x}) \cdot \left[\nabla_{\!\mathbf{x}} \varphi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) + \frac{1}{\varepsilon} \nabla_{\!\boldsymbol{\xi}} \varphi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \right] d\mathbf{x} = \int_{\text{Boundary}} \text{Something.}$$

Difficulty: ∇u^{ε} , $a^{\varepsilon}(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$, $\nabla_{\mathbf{x}}\varphi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$ and $\nabla_{\varepsilon}\varphi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$ converges in a weak sense only. Passing to the limit involves relatively sophisticated analytical methods.

Tools for mathematical justification of Asymptotic Expansion - 3 : Two-Scale Convergence

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Two-Scale Numerics Algorithms Implementati Two-Scale Convergence offers an efficient framework to pass to the limit in such terms, in the case when oscillations are periodic.

Link Homogenization - Two-Scale Convergence: Conclusion

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Two-Scale Numerics Algorithms Implementatio

- Two-Scale Convergence emerged as an efficient tools to justify Asymptotic Expansion
- Yet, it is more that this: It is a constructive Homogenization Method very well adapted to Singularly Perturbed Hyperbolic Equations.
- Well adapted for problems with oscillations at one frequency: ¹/₋
- Can be improved to the case of oscillations with several frequencies, if scale separation, for instance : $\frac{1}{c}$ and $\frac{1}{c^2}$.
- Cannot be improved to the case of several frequencies if no scale separation.
- Cannot be improved to the case of a variable frequency.

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Two proofs which are typical in Two-Scale Convergence

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The Riemann-Lebesgue Lemma

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The Lemma If $\psi \in L^{\infty}_{\#}(\mathbb{R})$. Defining $[\psi]^{\varepsilon}$ by $[\psi]^{\varepsilon}(x) = \psi(\frac{x}{\varepsilon})$, then $[\psi]^{\varepsilon} \rightarrow \int_{0}^{1} \psi(\xi) d\xi$ in $L^{\infty}(\mathbb{R})$ weak-*.

This means: for any test function φ

$$\int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \varphi(x) dx \to \int_{\mathbb{R}} \left(\int_{0}^{1} \psi(\xi) d\xi \right) \varphi(x) dx$$
$$= \int_{0}^{1} \psi(\xi) d\xi \int_{\mathbb{R}} \varphi(x) dx.$$

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The Riemann-Lebesgue Lemma proof - 1

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- Fix $\varphi \in \mathcal{D}(\mathbb{R})$
- Choose M s.t. supp $(\varphi) \subset [-M, M]$

Set

 $\{-M, -M + \varepsilon, \dots, -M + \mathbb{E}(2M/\varepsilon)\varepsilon, -M + (\mathbb{E}(2M/\varepsilon) + 1)\varepsilon \}$ (E: integer part)

• Split
$$\int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \varphi(x) dx = \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) \varphi(x) dx$$

• Use Taylor formula: $\forall x \in [-M + (i - 1)\varepsilon, -M + i\varepsilon],$ $\exists c_i(x) \in [-M + (i - 1)\varepsilon, x]$ such that $\varphi(x) = \varphi(-M + (i - 1)\varepsilon) + (x + M - (i - 1)\varepsilon)\varphi'(c_i(x))$ • $\int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \varphi(x) dx = \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) dx \varphi(-M(i - 1)\varepsilon)$ $+ \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) (x + M - (i - 1)\varepsilon)\varphi'(c_i(x)) dx$

The Riemann-Lebesgue Lemma proof - 2

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$$\int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \varphi(x) dx = \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) dx \varphi(-M(i-1)\varepsilon)$$

$$+ \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) (x+M-(i-1)\varepsilon)\varphi'(c_i(x)) dx$$

$$\begin{aligned} & = \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) \, dx \, \varphi(-M(i-1)\varepsilon) = \\ & \int_{0}^{1} \psi(\xi) \, d\xi \quad \varepsilon \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \varphi(-M(i-1)\varepsilon) \xrightarrow{\varepsilon \to 0} \int_{0}^{1} \psi(\xi) \, d\xi \, \int_{\mathbb{R}} \varphi(x) \, dx \end{aligned}$$
$$\\ & = \left| \sum_{i=1}^{\mathbb{E}(2M/\varepsilon)+1} \int_{-M+(i-1)\varepsilon}^{-M+i\varepsilon} \psi(\frac{x}{\varepsilon}) \, (x+M-(i-1)\varepsilon)\varphi'(c_i(x)) \, dx \right| \\ & \leq \int_{0}^{1} |\psi(\xi)| \, \varepsilon \, d\xi \, \left(\frac{2M+1}{\varepsilon} \right) \varepsilon \|\varphi'\|_{\infty} \xrightarrow{\varepsilon \to 0} 0 \end{aligned}$$

The Riemann-Lebesgue Lemma generalization

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The Lemma

If $\psi = \psi(x,\xi) \in C^0(\mathbb{R}; C^0_{\#}(\mathbb{R}))$. Defining $[\psi]^{\varepsilon}$ by $[\psi]^{\varepsilon}(x) = \psi(x, \frac{x}{\varepsilon})$, then

$$[\psi]^{\varepsilon}
ightarrow \int_{0}^{1} \psi(x,\xi) \, d\xi \text{ in } L^{\infty}(\mathbb{R}) \text{ weak-*}.$$

This means: for any test function φ

$$\int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \varphi(x) \, dx \to \int_{\mathbb{R}} \left(\int_{0}^{1} \psi(x,\xi) \, d\xi \right) \varphi(x) \, dx$$

i.e.: as soon as ε small enough,

$$\left|\int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \, \varphi(x) \, dx - \int_{\mathbb{R}} \left(\int_{0}^{1} \psi(x,\xi) \, d\xi \right) \varphi(x) \, dx \right| \text{ is small.}$$

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The Riemann-Lebesgue Lemma generalization proof - 1

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Typical proofs

step 1:

- $\forall m \in \mathbb{N}$: partition of [0, 1] with *m* intervals of length 1/m
- χ_i^m : characteristic functions of *i*-th interval, for i = 1..., mextended by periodicity over \mathbb{R} . ξ_i^m : center of the *i*-th interval

•
$$\tilde{\psi}_m(x,\xi) = \sum_{i=1}^m \psi(x,\xi_i^m) \chi_i^m(\xi) \xrightarrow{m \to \infty} \psi(x,\xi)$$

• $[\chi_i^m]^{\varepsilon} \xrightarrow{\varepsilon \to 0} \int_0^1 \chi_i^m(\xi) d\xi = \frac{1}{m} \text{ in } L^\infty(\mathbb{R}) \text{ weak-*.}$
Hence $[\tilde{\psi}_m]^{\varepsilon} \xrightarrow{\varepsilon \to 0} \sum_{i=1}^m \psi(x,\xi_i^m) \frac{1}{m} = \int_0^1 \tilde{\psi}_m(x,\xi) d\xi$

i=1

The Riemann-Lebesgue Lemma generalization proof - 2

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step 2:

$$\begin{split} \left| \int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \,\varphi(x) \,dx - \int_{\mathbb{R}} \left(\int_{0}^{1} \psi(x,\xi) \,d\xi \right) \varphi(x) \,dx \right| &\leq \\ \int_{\mathbb{R}} \left| [\psi]^{\varepsilon}(x) - [\tilde{\psi}_{m}]^{\varepsilon}(x) \right| \left| \varphi(x) \right| \,dx \\ &+ \left| \int_{\mathbb{R}} \left([\tilde{\psi}_{m}]^{\varepsilon}(x) - \int_{0}^{1} \tilde{\psi}_{m}(x,\xi) \,d\xi \right) \varphi(x) \,dx \right| \\ &+ \int_{\mathbb{R}} \left(\int_{0}^{1} \left| \tilde{\psi}_{m}(x,\xi) - \psi(x,\xi) \right| \,d\xi \right) \left| \varphi(x) \right| \,dx \end{split}$$

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The Riemann-Lebesgue Lemma generalization proof - 2

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step 2: Fix *m* s.t. :

$$\begin{split} \left| \int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \,\varphi(x) \,dx - \int_{\mathbb{R}} \left(\int_{0}^{1} \psi(x,\xi) \,d\xi \right) \varphi(x) \,dx \right| &\leq \\ \int_{\mathbb{R}} \left| [\psi]^{\varepsilon}(x) - [\tilde{\psi}_{m}]^{\varepsilon}(x) \right| \left| \varphi(x) \right| \,dx \quad \text{small for any } \varepsilon > 0 \\ &+ \left| \int_{\mathbb{R}} \left([\tilde{\psi}_{m}]^{\varepsilon}(x) - \int_{0}^{1} \tilde{\psi}_{m}(x,\xi) \,d\xi \right) \varphi(x) \,dx \right| \\ &+ \int_{\mathbb{R}} \left(\int_{0}^{1} \left| \tilde{\psi}_{m}(x,\xi) - \psi(x,\xi) \right| \,d\xi \right) \left| \varphi(x) \right| \,dx \quad \text{small} \end{split}$$

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The Riemann-Lebesgue Lemma generalization proof - 2

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step 2: Fix *m* and if ε is small:

$$\begin{aligned} \left| \int_{\mathbb{R}} [\psi]^{\varepsilon}(x) \varphi(x) \, dx - \int_{\mathbb{R}} \left(\int_{0}^{1} \psi(x,\xi) \, d\xi \right) \varphi(x) \, dx \right| &\leq \\ \int_{\mathbb{R}} \left| [\psi]^{\varepsilon}(x) - [\tilde{\psi}_{m}]^{\varepsilon}(x) \right| \left| \varphi(x) \right| \, dx \quad \text{small for any } \varepsilon > 0 \\ &+ \left| \int_{\mathbb{R}} \left([\tilde{\psi}_{m}]^{\varepsilon}(x) - \int_{0}^{1} \tilde{\psi}_{m}(x,\xi) \, d\xi \right) \varphi(x) \, dx \right| \quad \text{small} \\ &+ \int_{\mathbb{R}} \left(\int_{0}^{1} \left| \tilde{\psi}_{m}(x,\xi) - \psi(x,\xi) \right| \, d\xi \right) \left| \varphi(x) \right| \, dx \quad \text{small} \end{aligned}$$

is small

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Two-Scale Convergence: definitions and results

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Key Points of the Theory - 1

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Two-Scale Numerics Algorithms Implementat

- Several variants of the Two-Scale Convergence theory, for various targeted applications and involving various functional spaces.
- Very close to each other. All follow the same routine based :
 - A continuous injection Lemma
 - A compactness Theorem

G. Nguetseng.

A general convergence result for a functional related to the theory of homogenization.

SIAM Journal on Mathematical Analysis, 20(3):608–623, 1989.



See

$G. \ Nguetseng.$

Asymptotic analysis for a stiff variational problem arising in mechanics. SIAM Journal on Mathematical Analysis, 21(6):1394–1414, 1990.

G. Allaire.

Homogenization and Two-scale Convergence.

SIAM Journal on Mathematical Analysis, 23(6):1482-1518, 1992.

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Key Points of the Theory - 2

Two-Scale Convergence and Two-Scale Numerical Methods

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Definitions

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Definitions Notations

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- Ω : a regular domain in \mathbb{R}^n

•
$$q \in [1, +\infty)$$
 and $p \in (1, +\infty]$ s.t. $1/q + 1/p = 1$

- $C^0_{\#}(\mathbb{R}^n; \mathcal{L})$: continuous functions $\mathbb{R}^n \to \mathcal{L}$, periodic of period 1 with respect to every variable
- $L^p(\Omega, \mathcal{L}')$: functions $f : \Omega \to \mathcal{L}'$
 - s.t. $|f|_{\mathcal{L}'}^p$ is integrable if $p < \infty$
 - s.t. $|f|_{\mathcal{L}'}$ is essentially bounded if $p = \infty$
- $L^p_{\#}(\mathbb{R}^n; \mathcal{L}')$: functions $f : \mathbb{R}^n \to \mathcal{L}'$
 - s.t. $|f|_{\mathcal{L}'}^p$ is locally integrable if $p < \infty$
 - **s**.t. $|f|_{\mathcal{L}'}$ is locally essentially bounded if $p = \infty$

and periodic of period 1.

- $L^p_{\#}(\mathbb{R}^n; \mathcal{L}') = (L^q_{\#}(\mathbb{R}^n; \mathcal{L}))'$ (because of the separability of \mathcal{L})
- $L^q(\Omega; L^q_{\#}(\mathbb{R}^n, \mathcal{L})), L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})) \text{ and } L^p(\Omega; L^p_{\#}(\mathbb{R}^n, \mathcal{L}'))$

Definitions Two-Scale Convergence definition

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Two-Scale Numerics Algorithms Implementatio

Definition

$$(u^{\varepsilon}) = (u^{\varepsilon}(\mathbf{x})) \subset L^{p}(\Omega; \mathcal{L}')$$
 Two-Scale converges to
 $U = U(\mathbf{x}, \boldsymbol{\xi}) \in L^{p}(\Omega; L^{p}_{\#}(\mathbb{R}^{n}, \mathcal{L}'))$

if, for any function
$$\phi = \phi(\mathbf{x}, \boldsymbol{\xi}) \in L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))$$
,

$$\lim_{\varepsilon \to 0} \int_{\Omega} \ _{\mathcal{L}'} \langle u^{\varepsilon}(\mathsf{x}), \phi(\mathsf{x}, \frac{\mathsf{x}}{\varepsilon}) \rangle_{\!\mathcal{L}} \ d\mathsf{x} = \int_{\Omega} \int_{[0,1]^n} \ _{\mathcal{L}'} \langle U(\mathsf{x}, \boldsymbol{\xi}), \phi(\mathsf{x}, \boldsymbol{\xi}) \rangle_{\!\mathcal{L}} \ d\mathsf{x} d\boldsymbol{\xi},$$

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$(u^{\varepsilon}) = (u^{\varepsilon}(\mathbf{x})) \subset L^{2}(\Omega; \mathcal{L}')$ Two-Scale converges to $U = U(\mathbf{x}, \boldsymbol{\xi})$ and IF $U \in L^{2}(\Omega; \mathcal{C}^{0}_{\#}(\mathbb{R}^{n}; \mathcal{L}')).$

THEN we say

Definition

IF

IF p = q = 2, \mathcal{L} is a Hilbert space,

 $(u^{\varepsilon}) = (u^{\varepsilon}(\mathbf{x}))$ Strongly Two-Scale converges to $U = U(\mathbf{x}, \boldsymbol{\xi})$

if

$$\lim_{\varepsilon \to 0} \int_{\Omega} \left| u^{\varepsilon}(\mathbf{x}) - U(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \right|_{\mathcal{L}'}^2 d\mathbf{x} = 0$$

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Link with weak-* convergence

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Link with weak-* convergence

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Proposition

If $(u^{\varepsilon}) \subset L^{p}(\Omega; \mathcal{L}')$ Two-Scale converges to $U \in L^{p}(\Omega; L^{p}_{\#}(\mathbb{R}^{n}; \mathcal{L}'))$, then

$$u^{\varepsilon}
ightarrow \int_{[0,1]^n} U(.,\boldsymbol{\xi}) \ d\boldsymbol{\xi} \ \text{weak-* in } L^p(\Omega;\mathcal{L}')$$

In the definition of Two-Scale Convergence: $\phi(\mathbf{x}, \boldsymbol{\xi}) = \phi(\mathbf{x})$.

$$\begin{split} \lim_{\varepsilon \to 0} \int_{\Omega} \mathcal{L}' \langle u^{\varepsilon}(\mathbf{x}), \phi(\mathbf{x}) \rangle_{\mathcal{L}} \ d\mathbf{x} &= \int_{\Omega} \int_{[0,1]^n} \mathcal{L}' \langle U(\mathbf{x}, \boldsymbol{\xi}), \phi(\mathbf{x}) \rangle_{\mathcal{L}} \ d\mathbf{x} d\boldsymbol{\xi} = \\ &\int_{\Omega} \mathcal{L}' \langle \left(\int_{[0,1]^n} U(\mathbf{x}, \boldsymbol{\xi}) d\boldsymbol{\xi} \right), \phi(\mathbf{x}) \rangle_{\mathcal{L}} \ d\mathbf{x}. \end{split}$$

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Two-Scale Convergence criterion

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Two-Scale Convergence criterion Injection Lemma - 1

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Injection Lemma

If $\phi \in L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))$, then for all $\varepsilon > 0$, function $[\phi]^{\varepsilon} : \Omega \to \mathcal{L}$ defined by

$$[\phi]^{\varepsilon}(\mathbf{x}) = \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$$

satisfies

$$\|[\phi]^{\varepsilon}\|_{L^{q}(\Omega;\mathcal{L})} \leq \|\phi\|_{L^{q}(\Omega;\mathcal{C}^{\mathbf{0}}_{\#}(\mathbb{R}^{n};\mathcal{L}))}$$

$$egin{aligned} &\|\phi\|^q_{L^q(\Omega;\mathcal{C}^{\mathbf{0}}_{\#}(\mathbb{R}^n;\mathcal{L}))} = \int_{\Omega} \left(\sup_{oldsymbol{\xi}\in[0,1]^n} |\phi(\mathbf{x},oldsymbol{\xi})|_{\mathcal{L}}
ight)^q d\mathbf{x} \ &\|[\phi]^arepsilon\|_{L^q(\Omega;\mathcal{L})} = \int_{\Omega} \left|\phi(\mathbf{x},rac{\mathbf{x}}{arepsilon})
ight|^q_{\mathcal{L}} d\mathbf{x} \leq \int_{\Omega} \left(\sup_{oldsymbol{\xi}\in[0,1]^n} |\phi(\mathbf{x},oldsymbol{\xi})|_{\mathcal{L}}
ight)^q d\mathbf{x} \end{aligned}$$

Two-Scale Convergence criterion Injection Lemma - 2: Supplementary Proposition

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Supplementary Proposition

If $\phi \in L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))$, then

$$\begin{split} \lim_{\varepsilon \to 0} \| [\phi]^{\varepsilon} \|_{L^{q}(\Omega;\mathcal{L})}^{q} &= \lim_{\varepsilon \to 0} \int_{\Omega} \left| \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \right|_{\mathcal{L}}^{q} d\mathbf{x} \\ &= \int_{\Omega} \int_{[0,1]^{n}} |\phi(\mathbf{x}, \boldsymbol{\xi})|_{\mathcal{L}}^{q} d\mathbf{x} d\boldsymbol{\xi} = \| \phi \|_{L^{q}(\Omega; L^{q}_{\#}(\mathbb{R}^{n}; \mathcal{L}))}^{q} \end{split}$$

Two-Scale Convergence criterion The criterion - 1

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Theorem

If a sequence (u^{ε}) is bounded in $L^{p}(\Omega; \mathcal{L}')$, i.e. if

$$\|u^{arepsilon}\|_{L^p(\Omega;\mathcal{L}')} = \left(\int_{\Omega} |u^{arepsilon}(\mathbf{x})|^p_{\mathcal{L}'} \, d\mathbf{x}
ight)^{rac{\mathbf{1}}{p}} \leq c,$$

for a constant *c* independent of ε , then, there exists a profile $U \in L^p(\Omega; L^p_{\#}(\mathbb{R}^n; \mathcal{L}'))$ such that, up to a subsequence,

 (u^{ε}) Two-Scale converges to U.

Two ingredients for the proof

- sequential convergence
- Riesz Representation

Two-Scale Convergence criterion Proof of the Theorem - 1

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Two-Scale Numerics Algorithms Implementatio Injection Lemma and assumption of the Theorem \rightarrow $\forall \phi = \phi(\mathbf{x}, \boldsymbol{\xi}) \in L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})) \ ((1/p) + (1/q) = 1)$ $\left| \int_{\Omega} \mathcal{L}' \langle u^{\varepsilon}(\mathbf{x}), \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \rangle_{\mathcal{L}} d\mathbf{x} \right| \leq c \| [\phi]^{\varepsilon} \|_{L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))}$ $\leq c \| \phi \|_{L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))}$

Hence (thanks to the second inequality)

$$\begin{array}{rcl} \mu^{\varepsilon}: & L^{q}(\Omega; \mathcal{C}^{0}_{\#}(\mathbb{R}^{n}; \mathcal{L})) & \to & \mathbb{R} \\ & \phi & \mapsto & \int_{\Omega} \mathcal{L}' \langle u^{\varepsilon}(\mathbf{x}), \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \rangle_{\!\mathcal{L}} \ d\mathbf{x} \end{array}$$

bounded in $(L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})))'$ As $(L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})))'$ dual of separable space $L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))$ $\mu^{\varepsilon} \rightharpoonup \mu$ in $(L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})))'$ weak-* (up to a subsequence) In particular: $\langle \mu^{\varepsilon}, \phi \rangle \rightarrow \langle \mu, \phi \rangle, \forall \phi \in L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))_{\varepsilon}$

Two-Scale Convergence criterion Proof of the Theorem - 2

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We have:
$$\forall \phi = \phi(\mathbf{x}, \boldsymbol{\xi}) \in L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})) \ ((1/p) + (1/q) = 1)$$

 $\left| \int_{\Omega} \mathcal{L}' \langle u^{\varepsilon}(\mathbf{x}), \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \rangle_{\mathcal{L}} \ d\mathbf{x} \right| \leq c \| [\phi]^{\varepsilon} \|_{L^q(\Omega, \mathcal{L})} \leq c \| \phi \|_{L^q(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))}$
Making $\varepsilon \to 0 \to$

$$|\langle \mu, \phi
angle| \leq c \, \|\phi\|_{L^q(\Omega; L^q_\#(\mathbb{R}^n; \mathcal{L}))} \ \ orall \phi \in L^q(\Omega; \mathcal{C}^0_\#(\mathbb{R}^n; \mathcal{L}))$$

Since $L^{q}(\Omega; \mathcal{C}^{0}_{\#}(\mathbb{R}^{n}; \mathcal{L}))$ is dense in $L^{q}(\Omega; L^{q}_{\#}(\mathbb{R}^{n}; \mathcal{L}))$ (whose dual is $L^{p}(\Omega; L^{p}_{\#}(\mathbb{R}^{n}; \mathcal{L}')))$ Riez Representation Theorem $\rightarrow \exists U \in L^{p}(\Omega; L^{p}_{\#}(\mathbb{R}^{n}; \mathcal{L}'))$ s.t.

$$\langle \mu, \phi
angle = \int_\Omega \int_{[0,1]^n} {}_{\mathcal{L}'} \langle \mathit{U}(\mathsf{x}, oldsymbol{\xi}), \phi(\mathbf{x}, oldsymbol{\xi})
angle_{\mathcal{L}} \, d\mathsf{x} doldsymbol{\xi},$$

$$\int_{\Omega} \mathcal{L}' \langle u^{\varepsilon}(\mathbf{x}), \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \rangle_{\mathcal{L}} d\mathbf{x} \to \int_{\Omega} \int_{[0,1]^n} \mathcal{L}' \langle U(\mathbf{x}, \boldsymbol{\xi}), \phi(\mathbf{x}, \boldsymbol{\xi}) \rangle_{\mathcal{L}} d\mathbf{x} d\boldsymbol{\xi}$$

is $\varepsilon \to 0$

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Strong Two-Scale Convergence criterion

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Strong Two-Scale Convergence criterion Preliminary results -1

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Lemma

 $\mathsf{IF} \ \psi = \psi(\mathsf{x}, \boldsymbol{\xi}) \in L^2(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L}))$

 $([\psi]^{\varepsilon})$ Strongly Two-Scale converges to ψ

(recall: $[\psi]^{\varepsilon}(\mathbf{x}) = \psi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$)

step 1: Two-Scale convergence Consequence of the Riemann-Lebesgue generalization

$$\int_{\Omega} \mathcal{L} \langle \psi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}), \phi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon}) \rangle_{\mathcal{L}} \ d\mathbf{x} \to \int_{\Omega} \int_{[0,1]^n} \mathcal{L} \langle \psi(\mathbf{x}, \boldsymbol{\xi}), \phi(\mathbf{x}, \boldsymbol{\xi}) \rangle_{\mathcal{L}} \ d\mathbf{x} d\boldsymbol{\xi}$$

 $\forall \phi \in L^2(\Omega; \mathcal{C}^0_{\#}(\mathbb{R}^n; \mathcal{L})), \text{ i.e.}$

 $([\psi]^{\varepsilon})$ Two-Scale converges to ψ

Strong Two-Scale Convergence criterion Preliminary results - 2

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step 2: Strong Two-Scale convergence

$$\int_{\Omega} \left| [\psi]^{\varepsilon}(\mathsf{x}) - \psi(\mathsf{x}, \frac{\mathsf{x}}{\varepsilon}) \right|_{\mathcal{L}'}^{2} d\mathsf{x} \to 0.$$

Completely obvious: $[\psi]^{\varepsilon}(\mathbf{x}) = \psi(\mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$ Hence:

 $([\psi]^{\varepsilon})$ Strongly Two-Scale converges to ψ

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Strong Two-Scale Convergence criterion Preliminary results - 3

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Also easy to prove:

Lemma

$$\mathsf{IF}\,\,\psi=\psi(\mathsf{x},\boldsymbol{\xi})\in L^2(\Omega;\mathcal{C}^0_{\#}(\mathbb{R}^n;\mathcal{L}))$$

$$\begin{split} \|[\psi]^{\varepsilon}\|_{L^{2}(\Omega;\mathcal{L})} &= \left(\int_{\Omega} \left|\psi(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\right|_{\mathcal{L}}^{2} d\mathbf{x}\right)^{\frac{1}{2}} = \\ \int_{\Omega} \mathcal{L} \langle\psi(\mathbf{x},\frac{\mathbf{x}}{\varepsilon}),\psi(\mathbf{x},\frac{\mathbf{x}}{\varepsilon})\rangle_{\mathcal{L}} d\mathbf{x}\right)^{\frac{1}{2}} &\to \left(\int_{\Omega} \int_{[0,1]^{n}} \mathcal{L} \langle\psi(\mathbf{x},\boldsymbol{\xi}),\psi(\mathbf{x},\boldsymbol{\xi})\rangle_{\mathcal{L}} d\mathbf{x}d\boldsymbol{\xi}\right)^{\frac{1}{2}} \\ &= \left(\int_{\Omega} \int_{[0,1]^{n}} |\psi(\mathbf{x},\boldsymbol{\xi})|_{\mathcal{L}}^{2} d\mathbf{x}\right)^{\frac{1}{2}} = \|\psi\|_{L^{2}(\Omega;L^{2}_{\#}(\mathbb{R}^{n};\mathcal{L}))} \,. \end{split}$$

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Strong Two-Scale Convergence criterion The Criterion

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Theorem

$$\begin{split} \mathsf{IF}(u^\varepsilon) \subset L^2(\Omega;\mathcal{L}) \text{ Two-Scale converges to } U \\ \mathsf{IF} \ U \in L^2(\Omega;\mathcal{C}^0_\#(\mathbb{R}^n;\mathcal{L})) \\ \mathsf{IF} \end{split}$$

$$\lim_{\varepsilon \to 0} \|u^{\varepsilon}\|_{L^{2}(\Omega;\mathcal{L})} = \|U\|_{L^{2}(\Omega;L^{2}([0,1]^{n};\mathcal{L})},$$

THEN

 (u^{ε}) Strongly Two-Scale converges to U,

and, $\forall (v^{\varepsilon}) \subset L^2(\Omega; \mathcal{L})$ Two-Scale converging towards V,

$$\mathcal{L}\langle u^{\varepsilon}, v^{\varepsilon} \rangle_{\mathcal{L}} \rightharpoonup \int_{[0,1]^n} \mathcal{L}\langle U(.,\xi), V(.,\xi) \rangle_{\mathcal{L}} d\xi, \text{ in } \mathcal{D}'(\Omega).$$

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Homogenization of singularly perturbed Hyperbolic Partial Differential Equations

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Motivation : Tokamaks and Stellarators

Equation of interest

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Some words on Tokamaks and Stellarators - 1

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Some words on Tokamaks and Stellarators - 2

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Emmanuel Frénod Two-Scale Convergence and Two-Scale Numerical Methods

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Equation of interest and setting

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Equation of interest and setting

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$$\begin{split} &\frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}(t,\frac{t}{\varepsilon},\mathbf{x}) \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b}(\mathbf{x}) \cdot \nabla u^{\varepsilon} = 0\\ &u^{\varepsilon}_{|t=0} = u_{0}\\ &u^{\varepsilon} = u^{\varepsilon}(t,\mathbf{x}), \ \mathbf{x} \in \mathbb{R}^{d}, \ t \in [0,T), \ \text{for} \ T > 0 \end{split}$$

Assumptions:

- **a** is regular
- $\nabla \cdot \mathbf{a} = 0$
- $\tau \mapsto \mathbf{a}(t, \tau, \mathbf{x})$ periodic of period 1

b(
$$\mathbf{x}$$
) = $M\mathbf{x}$, M matrix s.t.

•
$$tr M = 0$$

•
$$\tau \mapsto e^{\tau M}$$
 periodic of period 1

$$\Rightarrow \nabla \cdot \mathbf{b} = 0 \text{ and } \tau \mapsto \mathbf{X}(\tau) = e^{\tau M} \mathbf{x} \text{ periodic of period } 1 \\ (\frac{\partial \mathbf{X}}{\partial \tau} = M \mathbf{X} = \mathbf{b}(\mathbf{X}), \ \mathbf{X}(0) = \mathbf{x}]$$

$$\mathbf{u}_0 \in L^2(\mathbb{R}^d)$$

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A priori estimate

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A priori estimate

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$$\begin{pmatrix} \frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla u^{\varepsilon} = 0 \end{pmatrix} \times u^{\varepsilon}, \quad \int_{\mathbb{R}^{d}} d\mathbf{x} \to \int_{\mathbb{R}^{d}} \frac{\partial u^{\varepsilon}}{\partial t} u^{\varepsilon} d\mathbf{x} + \int_{\mathbb{R}^{d}} \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot \nabla u^{\varepsilon} u^{\varepsilon} d\mathbf{x} + \frac{1}{\varepsilon} \int_{\mathbb{R}^{d}} \mathbf{b} \cdot \nabla u^{\varepsilon} u^{\varepsilon} d\mathbf{x} = 0$$

$$= \int_{\mathbb{R}^{d}} \frac{\partial u^{\varepsilon}}{\partial t} u^{\varepsilon} d\mathbf{x} = \frac{1}{2} \frac{d\left(\int_{\mathbb{R}^{d}} |u^{\varepsilon}|^{2} d\mathbf{x}\right)}{dt} = \frac{1}{2} \frac{d\left(\|u^{\varepsilon}\|_{L^{2}(\mathbb{R}^{d})}\right)}{dt}$$

$$= \int_{\mathbb{R}^{d}} \mathbf{a} \cdot \nabla u^{\varepsilon} u^{\varepsilon} d\mathbf{x} = -\int_{\mathbb{R}^{d}} \mathbf{a} \cdot \nabla u^{\varepsilon} u^{\varepsilon} d\mathbf{x} - \int_{\mathbb{R}^{d}} \nabla \cdot \mathbf{a} u^{\varepsilon} u^{\varepsilon} d\mathbf{x} = -\int_{\mathbb{R}^{d}} \mathbf{a} \cdot \nabla u^{\varepsilon} u^{\varepsilon} d\mathbf{x} = 0$$

$$= \text{Same thing for last term}$$

$$\frac{d\left(\|u^{\varepsilon}\|_{L^{2}(\mathbb{R}^{d})}\right)}{dt} = 0 \to \|u^{\varepsilon}\|_{L^{2}(\mathbb{R}^{d})} \text{ constant} \to \|u^{\varepsilon}\|_{L^{2}([0,T);L^{2}(\mathbb{R}^{d}))} \text{ bounded}$$

$$(u^{\varepsilon}) \text{ Two-Scale Converges to } U = U(t, \tau, \mathbf{x}) \in L^{2}([0,T); L^{2}_{\#}((\mathbb{R}; L^{2}(\mathbb{R}^{d})))$$

$$up \text{ to a subsequence}$$

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Weak Formulation with Oscillating Test Functions

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Order 0 Homogenization Weak Formulation With Oscillating Test Functions

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For
$$\phi = \phi(t, \tau, \mathbf{x})$$
 regular: $[\phi]^{\varepsilon}(t, \mathbf{x}) = \phi(t, \frac{t}{\varepsilon}, \mathbf{x})$

$$\frac{\partial [\phi]^{\varepsilon}}{\partial t} = \left[\frac{\partial \phi}{\partial t}\right]^{\varepsilon} + \frac{1}{\varepsilon} \left[\frac{\partial \phi}{\partial \tau}\right]^{\varepsilon}$$
$$[\phi]^{\varepsilon} \times \left(\frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla u^{\varepsilon}\right), \quad \int, \text{ IBP } \Rightarrow$$

$$\int_{0}^{T} \int_{\mathbb{R}^{d}} u^{\varepsilon} \left(\left[\frac{\partial \phi}{\partial t} \right]^{\varepsilon} + \frac{1}{\varepsilon} \left[\frac{\partial \phi}{\partial \tau} \right]^{\varepsilon} + \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot \left[\nabla \phi \right]^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \left[\nabla \phi \right]^{\varepsilon} \right) d\mathbf{x} dt + \int_{\mathbb{R}^{d}} u_{0} \phi(0, 0, .) d\mathbf{x} = 0$$

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Order 0 Homogenization - Constraint

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Order 0 Homogenization Constraint

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WFOTF:

$$\int_{0}^{T} \int_{\mathbb{R}^{d}} u^{\varepsilon} \left(\left[\frac{\partial \phi}{\partial t} \right]^{\varepsilon} + \frac{1}{\varepsilon} \left[\frac{\partial \phi}{\partial \tau} \right]^{\varepsilon} + \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot [\nabla \phi]^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot [\nabla \phi]^{\varepsilon} \right) d\mathbf{x} dt + \int_{\mathbb{R}^{d}} u_{0} \phi(0, 0, .) d\mathbf{x} = 0$$

$$\times \varepsilon, \ \varepsilon \to 0 \ \to$$

$$\frac{\partial U}{\partial \tau} + \mathbf{b} \cdot \nabla U = \mathbf{0}$$

$$\exists V(t, \mathbf{y}) \in L^{2}([0, T]; L^{2}(\mathbb{R}^{d})) \text{ s.t. } U(t, \tau, \mathbf{x}) = V(t, e^{-\tau M}\mathbf{x})$$

$$(\text{Recall: } \frac{\partial(e^{\tau M}\mathbf{x})}{\partial \tau} = M(e^{\tau M}\mathbf{x}) = \mathbf{b}(e^{\tau M}\mathbf{x})$$

$$\frac{\partial(V(t, e^{-\tau M}\mathbf{x}))}{\partial \tau} + \mathbf{b} \cdot \nabla(V(t, e^{-\tau M}\mathbf{x})) =$$

$$\nabla V(t, e^{-\tau M}\mathbf{x})) \cdot ((-e^{-\tau M})M\mathbf{x}) + ((e^{-\tau M})M\mathbf{x}) \cdot \nabla V(t, e^{-\tau M}\mathbf{x})) = 0) = 0$$

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Order 0 Homogenization - Equation for V

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Order 0 Homogenization Equation for V - 1

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For
$$\gamma = \gamma(t, \mathbf{y})$$
 regular: $\phi(t, \tau, \mathbf{x}) = \gamma(t, e^{-\tau M} \mathbf{x})$ s.t. $\frac{\partial \phi}{\partial \tau} + \mathbf{b} \cdot \nabla \phi = 0$
In WFOTF \rightarrow
 $\int_{0}^{T} \int_{\mathbb{R}^{d}} u^{\varepsilon} \left(\left[\frac{\partial \phi}{\partial t} \right]^{\varepsilon} + \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot \left[\nabla \phi \right]^{\varepsilon} \right) d\mathbf{x} dt + \int_{\mathbb{R}^{d}} u_{0} \phi(0, 0, .) d\mathbf{x} = 0$
 $\varepsilon \to 0 \rightarrow$

дф

$$\int_{0}^{T} \int_{0}^{1} \int_{\mathbb{R}^{d}} U(t,\tau,\mathbf{x}) \left(\frac{\partial \phi}{\partial t}(t,\tau,\mathbf{x}) + \mathbf{a}(t,\tau,\mathbf{x}) \cdot \nabla \phi(t,\tau,\mathbf{x}) \right) d\mathbf{x} d\tau dt + \int_{\mathbb{R}^{d}} u_{0} \phi(0,0,.) d\mathbf{x} = 0$$

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Order 0 Homogenization Equation for V - 2

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$$\int_{0}^{T} \int_{0}^{1} \int_{\mathbb{R}^{d}} U(t,\tau,\mathbf{x}) \left(\frac{\partial \phi}{\partial t}(t,\tau,\mathbf{x}) + \mathbf{a}(t,\tau,\mathbf{x}) \cdot \nabla \phi(t,\tau,\mathbf{x}) \right) d\mathbf{x} d\tau dt + \int_{\mathbb{R}^{d}} u_{0} \phi(0,0,.) d\mathbf{x} = 0$$

 $U \text{ in terms of } V; \phi \text{ in terms of } \gamma$ $\frac{\partial \phi}{\partial t}(t, \tau, \mathbf{x}) = \frac{\partial \gamma}{\partial t}(t, e^{-\tau M} \mathbf{x}) \text{ and } \nabla \phi(t, \tau, \mathbf{x}) = (e^{-\tau M})^T \nabla \gamma(t, e^{-\tau M} \mathbf{x})$ $\rightarrow \int_0^T \int_0^1 \int_{\mathbb{R}^d} V(t, \mathbf{y}) \left(\frac{\partial \gamma}{\partial t}(t, \mathbf{y}) + e^{-\tau M} \mathbf{a}(t, \tau, e^{\tau M} \mathbf{y}) \cdot \nabla \gamma(t, \mathbf{y})\right) d\mathbf{y} d\tau dt$ $+ \int_{\mathbb{R}^d} u_0(\mathbf{y}) \gamma(0, \mathbf{y}) d\mathbf{y} = 0$ $\frac{\partial V}{\partial t} + \left(\int_0^1 e^{-\sigma M} \mathbf{a}(t, \sigma, e^{\sigma M} \mathbf{y}) d\sigma\right) \cdot \nabla V = 0 \quad V_{|t=0} = u_0$

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Order 1 Homogenization

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To simplify computations :

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Two-Scale Numerics Algorithms Implementatio From now: $\mathbf{a}(t, \tau, \mathbf{x}) = \mathbf{a}(\mathbf{x})$

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Order 1 Homogenization - Preparations: Equation for U and u

Order 1 Homogenization Equation for U and u - 1

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Two-Scale Numerics Algorithms Implementation Linearity \rightarrow Equation for $U \rightarrow$ Equation for u (w-* limit of (u^{ε})): WRITE

$$\frac{\partial V}{\partial t} + \left(\int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) \, d\sigma\right) \cdot \nabla V = 0 \text{ in } \mathbf{y} = e^{-\tau M} \mathbf{x}$$

USE:
$$U(t, \tau, \mathbf{x}) = V(t, e^{-\tau M} \mathbf{x})$$

 $\nabla U(t, \tau, \mathbf{x}) = (e^{-\tau M})^T \nabla V(t, e^{-\tau M} \mathbf{x})$ i.e.
 $\nabla V(t, e^{-\tau M} \mathbf{x}) = (e^{\tau M})^T \nabla U(t, \tau, \mathbf{x}) \rightarrow$

$$D = \frac{\partial \left(V(t, e^{-\tau M} \mathbf{x}) \right)}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a} (e^{\sigma M} e^{-\tau M} \mathbf{x}) d\sigma \right) \cdot \nabla V(t, e^{-\tau M} \mathbf{x})$$
$$= \frac{\partial U}{\partial t} + \left(e^{\tau M} \int_{0}^{1} e^{-\sigma M} \mathbf{a} (e^{(\sigma - \tau)M} \mathbf{x}) d\sigma \right) \cdot \nabla U$$
$$= \frac{\partial U}{\partial t} + \left(\int_{0}^{1} e^{(\tau - \sigma)M} \mathbf{a} (e^{(\sigma - \tau)M} \mathbf{x}) d\sigma \right) \cdot \nabla U$$
$$= \frac{\partial U}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a} (e^{\sigma M} \mathbf{x}) d\sigma \right) \cdot \nabla U,$$

Order 1 Homogenization Equation for U and u - 2

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$$0 = \frac{\partial \left(V(t, e^{-\tau M} \mathbf{x})\right)}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} e^{-\tau M} \mathbf{x}) d\sigma\right) \cdot \nabla V(t, e^{-\tau M} \mathbf{x})$$
$$= \frac{\partial U}{\partial t} + \left(\int_{0}^{1} e^{(\tau - \sigma)M} \mathbf{a}(e^{(\sigma - \tau)M} \mathbf{x}) d\sigma\right) \cdot \nabla U$$
$$= \frac{\partial U}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla U,$$
$$\rightarrow$$
$$\frac{\partial U}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla U = 0, \quad U_{|t=0} = u_{0}(e^{-\tau M} \mathbf{x})$$
$$u = \int_{0}^{1} U(., \tau, .) d\tau \rightarrow$$
$$\frac{\partial u}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla u = 0, \quad u_{|t=0} = \int_{0}^{1} u_{0}(e^{-\tau M} \mathbf{x}) d\tau$$

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Order 1 Homogenization - Strong Two-Scale convergence of u^{ε}

Order 1 Homogenization Strong Two-Scale convergence of U - 1

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$$\frac{\partial (u^{\varepsilon})^2}{\partial t} = 2u^{\varepsilon} \frac{\partial u^{\varepsilon}}{\partial t} \quad \text{and} \quad \nabla (u^{\varepsilon})^2 = 2u^{\varepsilon} \, \nabla u^{\varepsilon}$$

multiplying equation for u^{ε} by $2u^{\varepsilon} \rightarrow$

$$\frac{\partial (u^{\varepsilon})^2}{\partial t} + \mathbf{a} \cdot \nabla (u^{\varepsilon})^2 + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla (u^{\varepsilon})^2 = 0 \quad (u^{\varepsilon})_{|t=0}^2 = u_0^2$$

IF $u_0^2 \in L^2(\mathbb{R}^d)$, *i.e.* if $u_0 \in L^4(\mathbb{R}^d)$, doing the same \rightarrow $(u^{\varepsilon})^2$ Two-Scale converges to Z solution to

$$\frac{\partial Z}{\partial t} + \left(\int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla Z = 0$$
$$Z_{|t=0} = u_0^2 (e^{-\tau M} \mathbf{x})$$

 $\rightarrow Z = U^2$

 $((u^{\varepsilon})^2)$ Two-Scale Converges to U^2

Order 1 Homogenization Strong Two-Scale convergence of U - 2

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$$\|u^{\varepsilon}\|_{L^{2}([0,T);L^{2}(\mathbb{R}^{d}))} \to \|U\|_{L^{2}([0,T);L^{2}_{\#}((\mathbb{R};L^{2}(\mathbb{R}^{d})))}$$

Moreover: IF
$$u_0 \in C^0(\mathbb{R}^d) \rightarrow u^{\varepsilon} \in C^0([0, T); C^0(\mathbb{R}^d)), U \in C^0([0, T); C^0_{\#}((\mathbb{R}; C^0(\mathbb{R}^d))), V \in C^0([0, T); C^0(\mathbb{R}^d)))$$

HENCE: IF $u_0 \in (L^2 \cap L^4 \cap C^0)(\mathbb{R}^d)$, THEN in addition to every already stated results

 (u^{ε}) Strongly Two-Scale Converges to U

(We have: $(u^{\varepsilon} - [U]^{\varepsilon}) \to 0$ Now: Get more: $((u^{\varepsilon} - [U]^{\varepsilon})/\varepsilon)$ Two-Scale Converges)

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Order 1 Homogenization - Function W_1

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Two-Scale Convergence and Two-Scale Numerical Methods Step 1:

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$$\begin{aligned} \frac{\partial U}{\partial \tau} + \mathbf{b} \cdot \nabla U &= 0 \rightarrow \frac{\partial [U]^{\varepsilon}}{\partial t} = \left[\frac{\partial U}{\partial t}\right]^{\varepsilon} + \frac{1}{\varepsilon} \left[\frac{\partial U}{\partial \tau}\right]^{\varepsilon} = \left[\frac{\partial U}{\partial t}\right]^{\varepsilon} - \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla [U]^{\varepsilon} \\ \frac{\partial U}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla U &= 0, \quad U_{|t=0} = u_{0}(e^{-\tau M} \mathbf{x}) \\ \frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}(\mathbf{x}) \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla u^{\varepsilon} = 0, \quad u^{\varepsilon}_{|t=0} = u_{0} \\ \rightarrow \\ \frac{\partial \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right)}{\partial t} + \mathbf{a} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right) + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right) \\ &= -\frac{1}{\varepsilon} \left(\mathbf{a} - \int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla [U]^{\varepsilon} \\ &\left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right)_{|t=0} = 0 \end{aligned}$$

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Step 2: DEFINE:
$$W_1 = W_1(t, \tau, \mathbf{y})$$
 s.t
 $\tilde{W}_1 = \tilde{W}_1(t, \tau, \mathbf{x}) = W_1(t, \tau, e^{-\tau M}\mathbf{x})$ solution to

$$\frac{\partial \tilde{W}_1}{\partial \tau} + \mathbf{b} \cdot \nabla \tilde{W}_1 = -\left(\mathbf{a} - \int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla U$$

THEN:
$$[ilde{\mathcal{W}}_1]^arepsilon = [ilde{\mathcal{W}}_1]^arepsilon(t, \mathbf{x}) = ilde{\mathcal{W}}_1(t, t/arepsilon, \mathbf{x})$$
:

$$\frac{\partial [\tilde{W}_{1}]^{\varepsilon}}{\partial t} + \mathbf{a} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} \\
= \left[\frac{\partial \tilde{W}_{1}}{\partial t} \right]^{\varepsilon} + \frac{1}{\varepsilon} \left[\frac{\partial \tilde{W}_{1}}{\partial \tau} \right]^{\varepsilon} + \mathbf{a} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} \\
= \left[\frac{\partial \tilde{W}_{1}}{\partial t} \right]^{\varepsilon} + \mathbf{a} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} - \frac{1}{\varepsilon} \left(\mathbf{a} - \int_{0}^{1} e^{-\sigma M} \mathbf{a} (e^{\sigma M} \mathbf{x}) d\sigma \right) \cdot \nabla [U]^{\varepsilon}$$

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$$\begin{aligned} \frac{\partial \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right)}{\partial t} + \mathbf{a} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right) + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right) \\ &= -\frac{1}{\varepsilon} \left(\mathbf{a} - \int_{\mathbf{0}}^{\mathbf{1}} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla [U]^{\varepsilon} \\ \frac{\partial [\tilde{W}_{\mathbf{1}}]^{\varepsilon}}{\partial t} + \mathbf{a} \cdot \nabla [\tilde{W}_{\mathbf{1}}]^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla [\tilde{W}_{\mathbf{1}}]^{\varepsilon} \\ &= \left[\frac{\partial \tilde{W}_{\mathbf{1}}}{\partial t}\right]^{\varepsilon} + \mathbf{a} \cdot \nabla [\tilde{W}_{\mathbf{1}}]^{\varepsilon} - \frac{1}{\varepsilon} \left(\mathbf{a} - \int_{\mathbf{0}}^{\mathbf{1}} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{x}) d\sigma\right) \cdot \nabla [U]^{\varepsilon} \end{aligned}$$

$$\frac{\partial \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right)}{\partial t} + \mathbf{a} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right) \\ + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right) = -\left[\frac{\partial \tilde{W}_{1}}{\partial t}\right]^{\varepsilon} - \mathbf{a} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} \\ \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right)_{|t=0} = -[\tilde{W}_{1}]^{\varepsilon}_{|t=0}$$

Step 3: expression of the function W_1 :

$$\begin{split} \tilde{W}_{1}(t,\tau,\mathbf{x}) &= W_{1}(t,\tau,e^{-\tau M}\mathbf{x}) \\ \frac{\partial \tilde{W}_{1}}{\partial \tau} + \mathbf{b} \cdot \nabla \tilde{W}_{1} &= -\left(\mathbf{a} - \int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M}\mathbf{x}) d\sigma\right) \cdot \nabla U \\ \rightarrow \\ \frac{\partial W_{1}}{\partial \tau} &= -\left(\mathbf{a}(e^{\tau M}\mathbf{y}) - \int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{(\sigma+\tau)M}\mathbf{y}) d\sigma\right) \cdot \nabla U(t,\tau,e^{\tau M}\mathbf{y}) \\ \nabla U(t,\tau,e^{\tau M}\mathbf{y}) &= (e^{-\tau M})^{T} \nabla (U(t,\tau,e^{\tau M}\mathbf{y})) = (e^{-\tau M})^{T} \nabla V(t,\mathbf{y}) \end{split}$$

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$$\frac{\partial W_1}{\partial \tau} = -\left(e^{-\tau M}\mathbf{a}(e^{\tau M}\mathbf{y}) - \int_0^1 e^{-(\sigma+\tau)M}\mathbf{a}(e^{(\sigma+\tau)M}\mathbf{y})\,d\sigma\right)\cdot\nabla V(t,\mathbf{y})$$
$$= -\left(e^{-\tau M}\mathbf{a}(e^{\tau M}\mathbf{y}) - \int_0^1 e^{-\sigma M}\mathbf{a}(e^{\sigma M}\mathbf{y})\,d\sigma\right)\cdot\nabla V(t,\mathbf{y})$$

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$$\frac{\partial W_1}{\partial \tau} = -\left(e^{-\tau M}\mathbf{a}(e^{\tau M}\mathbf{y}) - \int_0^1 e^{-(\sigma+\tau)M}\mathbf{a}(e^{(\sigma+\tau)M}\mathbf{y})\,d\sigma\right)\cdot\nabla V(t,\mathbf{y})$$
$$= -\left(e^{-\tau M}\mathbf{a}(e^{\tau M}\mathbf{y}) - \int_0^1 e^{-\sigma M}\mathbf{a}(e^{\sigma M}\mathbf{y})\,d\sigma\right)\cdot\nabla V(t,\mathbf{y})$$

$$W_{1}(t,\tau,\mathbf{y}) = -\left(\int_{0}^{\tau} e^{-\sigma M} \mathbf{a}(e^{\sigma M}\mathbf{y}) \, d\sigma - \tau \int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M}\mathbf{y}) \, d\sigma\right) \cdot \nabla V(t,\mathbf{y})$$

By-product: $[ilde{W}_1]^{arepsilon}_{|t=0}=0$

$$\left\|-\left[\frac{\partial \tilde{W}_1}{\partial t}\right]^{\varepsilon} - \mathbf{a} \cdot \nabla[\tilde{W}_1]^{\varepsilon}\right\|_{L^{\infty}([0,T);L^2(\mathbb{R}^d))} \leq C_1$$

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Order 1 Homogenization - A priori estimate and convergence

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Order 1 Homogenization A priori estimate and convergence - 1

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$$\frac{\partial \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right)}{\partial t} + \mathbf{a} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right) \\ + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right) = -\left[\frac{\partial \tilde{W}_{1}}{\partial t}\right]^{\varepsilon} - \mathbf{a} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} \\ \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right)_{|t=0} = -[\tilde{W}_{1}]^{\varepsilon}_{|t=0} = 0 \\ \times ((u^{\varepsilon} - [U]^{\varepsilon})/\varepsilon - [\tilde{W}_{1}]^{\varepsilon}), \int_{\mathbb{R}^{d}} d\mathbf{x}, \text{ IBP } \rightarrow \\ \frac{1}{\varepsilon} \left(\frac{\int_{\mathbb{R}^{d}} \left|\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right|^{2} d\mathbf{x}\right)}{dt} \le C_{1} \left(\int_{\mathbb{R}^{d}} \left|\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon}\right|^{2} d\mathbf{x}\right)^{\frac{1}{2}}$$

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$$\left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_1]^{\varepsilon}\right) \text{ and consequently } \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon}\right)$$

bounded in $L^2([0, T); L^2(\mathbb{R}^d))$. Then, up to subsequences,

$$\begin{pmatrix} \frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} \end{pmatrix} \text{ Two-Scale Converges to } U_1 = U_1(t, \tau, \mathbf{x}) \\ \begin{pmatrix} \frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_1]^{\varepsilon} \end{pmatrix} \text{ Two-Scale Converges to } U_1 - \tilde{W}_1 \end{cases}$$

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$$\mathsf{WFOTF}: \phi = \phi(t, \tau, \mathbf{x}) \in \mathcal{C}^1([0, T); \mathcal{C}^1_\#((\mathbb{R}; \mathcal{C}^1(\mathbb{R}^d)))$$

$$\int_{0}^{T} \int_{\mathbb{R}^{d}} \left(\frac{u^{\varepsilon} - [U]^{\varepsilon}}{\varepsilon} - [\tilde{W}_{1}]^{\varepsilon} \right) \left(\left[\frac{\partial \phi}{\partial t} \right]^{\varepsilon} + \frac{1}{\varepsilon} \left[\frac{\partial \phi}{\partial \tau} \right]^{\varepsilon} + \mathbf{a} \cdot [\nabla \phi]^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot [\nabla \phi]^{\varepsilon} \right) d\mathbf{x} dt$$
$$= \int_{0}^{T} \int_{\mathbb{R}^{d}} \left(- \left[\frac{\partial \tilde{W}_{1}}{\partial t} \right]^{\varepsilon} - \mathbf{a} \cdot \nabla [\tilde{W}_{1}]^{\varepsilon} \right) [\phi]^{\varepsilon} d\mathbf{x} dt$$

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$$rac{\partial (U_1 - ilde{W}_1)}{\partial au} + \mathbf{b} \cdot
abla (U_1 - ilde{W}_1) = 0$$

$$\exists V_1 = V_1(t, \mathbf{y}) \in L^2([0, T); L^2(\mathbb{R}^d)) \text{ s.t.}$$
$$U_1(t, \tau, \mathbf{x}) - \tilde{W}_1(t, \tau, \mathbf{x}) = V_1(t, e^{-\tau M} \mathbf{x}) \text{ i.e.}$$
$$U_1(t, \tau, \mathbf{x}) = V_1(t, e^{-\tau M} \mathbf{x}) + W_1(t, \tau, e^{-\tau M} \mathbf{x})$$

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Order 1 Homogenization - Equation for V_1

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For
$$\gamma = \gamma(t, \mathbf{y})$$
 regular: $\phi(t, \tau, \mathbf{x}) = \gamma(t, e^{-\tau M} \mathbf{x})$ s.t. $\frac{\partial \phi}{\partial \tau} + \mathbf{b} \cdot \nabla \phi = 0$
USE $\phi(t, \tau, \mathbf{x})$ in WFOTF, $\varepsilon \to 0 \to$
 $\int_0^T \int_0^1 \int_{\mathbb{R}^d} V_1(t, e^{-\tau M} \mathbf{x}) \left(\frac{\partial \gamma}{\partial t}(t, e^{-\tau M} \mathbf{x}) + e^{-\tau M} \mathbf{a}(\mathbf{x}) \cdot \nabla \gamma(t, e^{-\tau M} \mathbf{x}) \right) d\mathbf{x} d\tau dt$
 $= \int_0^T \int_0^1 \int_{\mathbb{R}^d} \left(-\frac{\partial \tilde{W}_1}{\partial t} - \mathbf{a}(\mathbf{x}) \cdot \nabla \tilde{W}_1 \right) \gamma(t, e^{-\tau M} \mathbf{x}) d\mathbf{x} d\tau dt$

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change of variables $(t, au, \mathbf{x}) \mapsto (t, au, \mathbf{y} = e^{- au M} \mathbf{x})$ gives

$$\int_{0}^{T} \int_{0}^{1} \int_{\mathbb{R}^{d}} V_{1}(t, \mathbf{y}) \left(\frac{\partial \gamma}{\partial t}(t, \mathbf{y}) + e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \cdot \nabla \gamma(t, \mathbf{y}) \right) d\mathbf{y} d\tau dt$$
$$= \int_{0}^{T} \int_{0}^{1} \int_{\mathbb{R}^{d}} \left(-\frac{\partial W_{1}}{\partial t} - e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \cdot \nabla W_{1} \right) \gamma(t, \mathbf{y}) d\mathbf{y} d\tau dt$$

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Order 1 Homogenization Equation for V_1 - 2

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$$\int_{0}^{T} \int_{0}^{1} \int_{\mathbb{R}^{d}} V_{1}(t, \mathbf{y}) \left(\frac{\partial \gamma}{\partial t}(t, \mathbf{y}) + e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \cdot \nabla \gamma(t, \mathbf{y}) \right) d\mathbf{y} d\tau dt$$
$$= \int_{0}^{T} \int_{0}^{1} \int_{\mathbb{R}^{d}} \left(-\frac{\partial W_{1}}{\partial t} - e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \cdot \nabla W_{1} \right) \gamma(t, \mathbf{y}) d\mathbf{y} d\tau dt$$

$$\begin{split} \frac{\partial V_1}{\partial t} + \left(\int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) d\sigma \right) \cdot \nabla V_1 = \\ \int_0^1 \left(-\frac{\partial W_1}{\partial t} - e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \cdot \nabla W_1 \right) d\tau \\ V_{1|t=0} = 0 \end{split}$$

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Order 1 Homogenization Equation for V_1 - 3

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$$\int_0^1 \left(-\frac{\partial W_1}{\partial t} - e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \cdot \nabla W_1 \right) d\tau$$

$$\begin{aligned} \frac{\partial V_1}{\partial t} + \left(\int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) d\sigma \right) \cdot \nabla V_1 = \\ \left(\int_0^1 \left(\left[\nabla \left[e^{-\tau M} \mathbf{a}(e^{\tau M} \mathbf{y}) \right] \right] \left(\int_0^\tau e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) \right) d\tau \right. \\ \left. + \frac{1}{2} \left[\nabla \left[\int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) d\sigma \right] \right] \left(\int_0^1 e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) d\sigma \right) \right) \right) \cdot (\nabla V) \\ V_{1|t=0} = 0. \end{aligned}$$

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Long term target : 10 ms of a Tokamak working

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To compute u^{ε} solution to

$$\frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}(t, \frac{t}{\varepsilon}, \mathbf{x}) \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla u^{\varepsilon} = 0 \qquad u^{\varepsilon}|_{t=0} = u_0.$$

for ε small:

Compute V solution to

$$\frac{\partial V}{\partial t} + \left(\int_0^1 e^{-\sigma M} \mathbf{a}(t, \sigma, e^{\sigma M} \mathbf{y}) \, d\sigma \right) \cdot \nabla V = 0 \quad V_{|t=0} = u_0$$

And use

$$u^{arepsilon}(t,\mathbf{x})\sim U(t,rac{t}{arepsilon},\mathbf{x}) \qquad U(t,rac{t}{arepsilon},\mathbf{x})=V(t,e^{-rac{t}{arepsilon}M}\mathbf{x})$$

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Two-Scale Numerics

Algorithms Implementati For ε small, to compute u^{ε} solution to

$$\frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}(\mathbf{x}) \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla u^{\varepsilon} = 0 \qquad u^{\varepsilon}|_{t=0} = u_0.$$

Compute: $W_1(t, \tau, \mathbf{y}) =$

$$-\left(\int_0^\tau e^{-\sigma M} \mathsf{a}(e^{\sigma M}\mathsf{y})\,d\sigma - \tau\int_0^1 e^{-\sigma M} \mathsf{a}(e^{\sigma M}\mathsf{y})\,d\sigma\right)\cdot \nabla V(t,\mathsf{y})$$

Compute: V and V_1 solution to

$$\frac{\partial V}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) d\sigma\right) \cdot \nabla V = 0 \quad V_{|t=0} = u_{0}$$
$$\frac{\partial V_{1}}{\partial t} + \left(\int_{0}^{1} e^{-\sigma M} \mathbf{a}(e^{\sigma M} \mathbf{y}) d\sigma\right) \cdot \nabla V_{1} = RHS(V)$$

And use $u^{\varepsilon}(t, t)$

$$\begin{split} \varepsilon(t,\mathbf{x}) &\sim U(t,\frac{t}{\varepsilon},\mathbf{x}) + \varepsilon U_1(t,\frac{t}{\varepsilon},\mathbf{x}) \\ &= V(t,e^{-\frac{t}{\varepsilon}M}\mathbf{x}) + \varepsilon (V_1(t,e^{-\frac{t}{\varepsilon}M}\mathbf{x}) + W_1(t,\frac{t}{\varepsilon},e^{-\frac{t}{\varepsilon}M}\mathbf{x})) \end{split}$$

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Hyperboli PDEs Order 0

Order 1

Two-Scale Numerics Algorithms

Implementation

Two-Scale Numerical Method implementation for beam simulation

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A beam in a focusing channel

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A beam in a focusing channel



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A beam in a focusing channel - Simulation

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Digression on Pic Methods

Pic Method explained - 1

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Beam in a focusing channel : PDE Model

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PDE Model

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Implementation

$$f_{\varepsilon} = f_{\varepsilon}(t, r, v_r), t \in [0, T), r \in \mathbb{R}^+ \text{ and } v_r \in \mathbb{R}$$
:

$$\begin{cases} \frac{\partial f_{\varepsilon}}{\partial t} + \frac{2\pi}{\varepsilon} v_{r} \frac{\partial f_{\varepsilon}}{\partial r} + \left(\mathbf{E}_{r\varepsilon} - \frac{2\pi}{\varepsilon} r \right) \frac{\partial f_{\varepsilon}}{\partial v_{r}} = 0\\ \frac{1}{r} \frac{\partial (r \mathbf{E}_{r\varepsilon})}{\partial r} = \rho_{\varepsilon}(t, r), \qquad \rho_{\varepsilon}(t, r) = \int_{\mathbb{R}} f_{\varepsilon}(t, r, v_{r}) dv_{r}\\ f_{\varepsilon}(t = 0, r, v_{r}) = f_{0} \end{cases}$$

 $\frac{\partial u^{\varepsilon}}{\partial t} + \mathbf{a}^{\varepsilon} \cdot \nabla u^{\varepsilon} + \frac{1}{\varepsilon} \mathbf{b} \cdot \nabla u^{\varepsilon} = 0 \text{ with } \mathbf{x} \text{ replaced by } (r, v_r) \text{ and}$

$$\mathbf{a}^{\varepsilon} = \begin{pmatrix} 0 \\ \mathbf{E}_{r_{\varepsilon}}(t, r) \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 2\pi v_{r} \\ -2\pi r \end{pmatrix}$$
$$M = \begin{pmatrix} 0 & 2\pi \\ -2\pi & 0 \end{pmatrix} e^{\tau M} = \begin{pmatrix} \cos(2\pi\tau) & \sin(2\pi\tau) \\ -\sin(2\pi\tau) & \cos(2\pi\tau) \end{pmatrix}$$

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Order 0 Homogenization

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Numerics Algorithms Implementation

Assumptions:
$$f_0 \ge 0, f_0 \in (L^1 \cap L^p)(\mathbb{R}^2; rdrdv_r)$$
 for $p \ge 2$
$$\int_{\mathbb{R}^2} (r^2 + v_r^2) f_0 rdrdv_r < +\infty$$

Then:

 f_{ε} Two-Scale Converges to $F \in L^{\infty}([0, T); L^{\infty}_{\#}(\mathbb{R}; L^{2}(\mathbb{R}^{2}; rdrdv_{r})))$ $\mathbf{E}_{r_{\varepsilon}}$ Two-Scale Converges to $\mathcal{E}_{r} \in L^{\infty}([0, T); L^{\infty}_{\#}(\mathbb{R}; W^{1,3/2}(\mathbb{R}; rdr)))$ $\exists G = G(t, q, u_r) \in L^{\infty}([0, T); L^2(\mathbb{R}^2; adadu_r))$: $F(t,\tau,r,v_r) = G(t,\cos(2\pi\tau)r - \sin(2\pi\tau)v_r,\sin(2\pi\tau)r + \cos(2\pi\tau)v_r)$ $\begin{cases} \frac{\partial G}{\partial t} + \int_{0}^{1} -\sin(2\pi\sigma)\mathcal{E}_{r}(t,\sigma,\cos(2\pi\sigma)q + \sin(2\pi\sigma)u_{r})\,d\sigma\,\frac{\partial G}{\partial q} \\ + \int_{0}^{1}\cos(2\pi\sigma)\mathcal{E}_{r}(t,\sigma,\cos(2\pi\sigma)q + \sin(2\pi\sigma)u_{r})\,d\sigma\,\frac{\partial G}{\partial u_{r}} = 0 \\ G(t=0) = f_{0} \end{cases}$ $\mathcal{E}_r = \mathcal{E}_r(t, \tau, r, v_r)$ $\frac{1}{r}\frac{\partial(r\mathcal{E}_r)}{\partial r} = \int_{\mathbb{T}} G(t, \cos(2\pi\tau)r - \sin(2\pi\tau)v_r, \sin(2\pi\tau)r + \cos(2\pi\tau)v_r) dv_r$ Two-Scale Convergence and Two-Scale Numerical Methods

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Two-Scale Pic Method for a beam in a focusing channel

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Two-Scale Pic Method to compute G - 1 Introduction

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G approximated by
$$G_N(q, u, t) = \sum_{k=1}^{N} w_k \delta(q - Q_k(t)) \delta(u - U_k(t))$$

From (Q_k^l, U_k^l) at time t_l , compute (Q_k^{l+1}, U_k^{l+1}) as an approximated solution to

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$$\frac{dQ_k}{dt} = -\int_0^1 \sin(2\pi\sigma) \mathcal{E}_r(t,\sigma,\cos(2\pi\sigma)Q_k + \sin(2\pi\sigma)U_k) \, d\sigma, \ Q_k(t_l) = Q'_k$$
$$\frac{dU_k}{dt} = \int_0^1 \cos(2\pi\sigma) \mathcal{E}_r(t,\sigma,\cos(2\pi\sigma)Q_k + \sin(2\pi\sigma)U_k) \, d\sigma, \quad U_k(t_l) = U'_k$$

at time $t_{l+1} = t_l + \Delta t$

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Two-Scale Pic Method to compute G - 1 Recall Runge-Kutta 4 Method

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Two-Scale Numerics Algorithms Implementation

$$t_{l,1} = t_l, \quad y^{l,1} = y^l$$

$$t_{l,2} = t_l + \frac{\Delta t}{2}, \quad y^{l,2} = y^l + \frac{1}{2}l^1 \text{ with } l^1 = \Delta t \ \mathcal{K}(t_{l,1}, y^{l,1}),$$

$$t_{l,3} = t_l + \frac{\Delta t}{2}, \quad y^{l,3} = y^l + \frac{1}{2}l^2 \text{ with } l^2 = \Delta t \ \mathcal{K}(t_{l,2}, y^{l,2}),$$

$$t_{l,4} = t_l + \Delta t, \quad y^{l,4} = y^l + l^3, \text{ with } l^3 = \Delta t \ \mathcal{K}(t_{l,3}, y^{l,3})$$

$$y^{l+1} = y^{l} + \frac{1}{6}l^{1} + \frac{1}{3}l^{2} + \frac{1}{3}l^{3} + \frac{1}{6}l^{4}$$
 with $l^{4} = \Delta t \, K(t_{l,4}, y^{l,4})$

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Two-Scale Pic Method to compute G - 1 Implementation - 1

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Two-Scale Numerics Algorithms Implementation In other words, we have to compute $Q_k^{l,2}$ as follows:

$$Q_k^{l,2} = Q_k^l + \frac{1}{2}I^1 \text{ with}$$
$$I^1 = \Delta t \Big(-\sum_{m=1}^p \gamma_m \sin(2\pi\sigma_m) \mathcal{E}_r(t_l, \sigma_m, \cos(2\pi\sigma_m)Q_k^l + \sin(2\pi\sigma_m)U_k^l) \Big)$$

$$Q_k^{l,3} = Q_k^l + \frac{1}{2}l^2 \text{ with}$$

$$l^2 = \Delta t \left(-\sum_{m=1}^p \gamma_m \sin(2\pi\sigma_m) \right)$$

$$\mathcal{E}_r^2(t_l + \frac{\Delta t}{2}, \sigma_m, \cos(2\pi\sigma_m)Q_k^{l,2} + \sin(2\pi\sigma_m)U_k^{l,2}) \right)$$

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Two-Scale Pic Method to compute G - 1 Implementation - 2

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Two-Scale Numerics Algorithms Implementation

$$Q_k^{l,4} = Q_k^l + l^3, \text{ with}$$

$$l^3 = \Delta t \left(-\sum_{m=1}^p \gamma_m \sin(2\pi\sigma_m) \right)$$

$$\mathcal{E}_r^3(t_l + \frac{\Delta t}{2}, \sigma_m, \cos(2\pi\sigma_m)Q_k^{l,3} + \sin(2\pi\sigma_m)U_k^{l,3}) \right)$$

$$Q_k^{l+1} = Q_k^l + rac{1}{6}l^1 + rac{1}{3}l^2 + rac{1}{3}l^3 + rac{1}{6}l^4, ext{ with }$$

D

$$I^{4} = \Delta t \Big(-\sum_{m=1}^{l} \gamma_{m} \sin(2\pi\sigma_{m}) \\ \mathcal{E}_{r}^{4}(t_{l} + \Delta t, \sigma_{m}, \cos(2\pi\sigma_{m})Q_{k}^{l,4} + \sin(2\pi\sigma_{m})U_{k}^{l,4}) \Big)$$

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